



NTNU – Trondheim
Norwegian University of
Science and Technology

Dataflow Analysis Framework: Summary and precision

We have looked at

- Live Variables
- Available Expressions
- Reaching Definitions
- Copy Propagation
 - as instances of a general dataflow analysis method
 - as points in a control flow graph
 - as data flow equations that associate sets with the points
 - as positions in a partial order (lattice) of possible sets
- Today, we'll add one more (Constant Folding) and look at how good our iterative solution is



Constant Folding (and propagation)

- The domain we're after is *pairs of variables, and their constant values*.
 - Obviously, not every variable will *have* a constant value, more in a minute
- Forward analysis
 - Traces paths from a point where a variable may be constant, to any point where we have determined that it isn't
- An intersection meet operator (of sorts)
 - A constant value must be the same along every path, otherwise it isn't very constant

Three levels of information

- We can say three things about the constant-ness of a variable X
 - 1) X may be a constant, but we haven't found its value yet
 - 2) X may be a constant, its value has only been 36 (or some other number)
 - 3) X is not constant, we've seen changes in its value
- We can order these observations according to how much we've found out about X :
 - $X = \top$ ← Can't say anything about X yet ("least precise knowledge")
 - $X = 21$ ← X is 21 somewhere in the program
 - $X = \perp$ ← X is not 21 everywhere ("most precise knowledge")



The program logic

- An assignment of a constant to a variable ($v=c$) generates that pair as a possibly constant value

$$\text{gen } [l] = \{v=c\}$$

- It also destroys the possibility that v is any other constant than c

$$\text{kill } [l] = \{v=n \text{ where } n \neq c\}$$

- An assignment of an expression ($v=u+w$) generates a possibly constant value if all its terms are constant

$$\text{gen } [l] = \{v=k\} \quad \text{kill } [l] = \{v=n \text{ where } n \neq k\}$$

$$k=u+w \text{ if } u,w \text{ are constants}$$

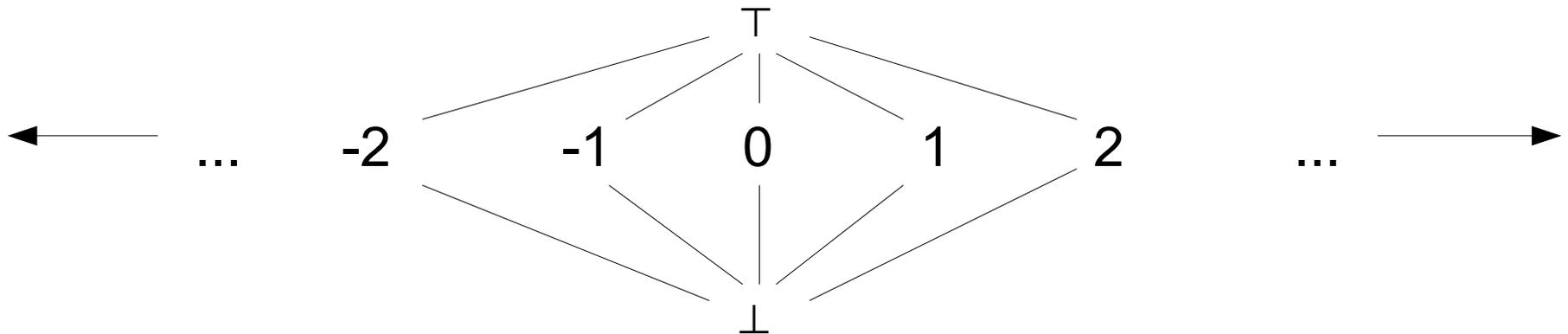
$$k= \perp \text{ if } u \text{ or } w \text{ are } \perp \quad (\text{known to be not-constant})$$

$$k= T \text{ otherwise}$$



If we draw the three levels

- There is an infinity of constants
- “X=36” is as informative as “X=21”, but taken together, they say that X is neither 36 nor 21 *always*
- A lattice of more and less informative levels becomes

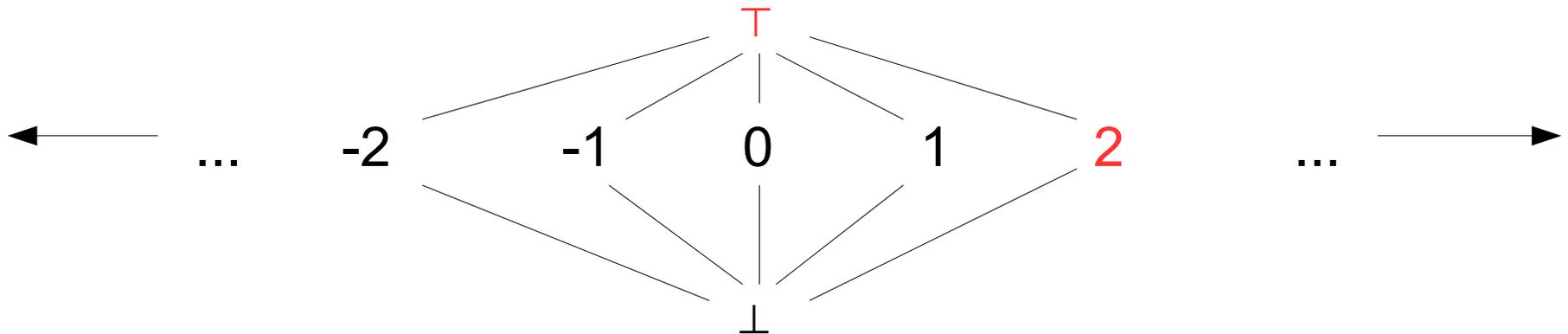


(It's infinitely wide, but has finite height)



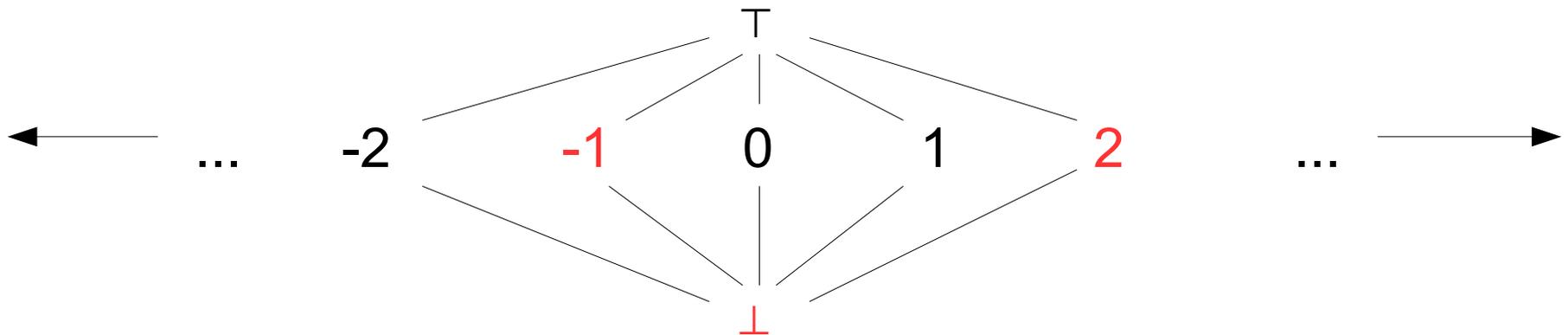
When $X=T$ meets $X=2$

- One set of observations haven't seen any value for X
- The other has only seen that $X = 2$
- X could be the constant 2
- $\{X=T\} \sqcap \{X=2\}$ gives $\{X=2\}$ (greatest lower bound in the order)



When $X=-1$ meets $X=2$

- One set of observations have only seen that $X=-1$
- The other has only seen that $X = 2$
- X can't be a constant, there are two different values
- $\{X=-1\} \sqcap \{X=2\}$ gives $\{X=\perp\}$ (greatest lower bound in the order)



Part of a meet operator

- This ordering relation of

$$\perp \sqsubseteq (\text{numbers}) \sqsubseteq \top$$

and the meet operator

$$p \sqcap q = \text{glb} (p, q) \text{ (in our constants-lattice)}$$

gives how to handle multiple observations about one variable

- The p-s and q-s here are set elements like “X=64”, “X= \perp ”, “X= \top ”, *et cetera*.
- Those all talk about one variable
- “Y=27”, “Y=13”, “Y= \top ” are positions in a separate lattice, which describes the constant-ness of Y
(that has the exact same structure)



When there are more variables

- The domain of the Constant Folding analysis is sets of bindings to values

$$\{v_1=c_1, v_2=c_2, v_3=c_3, \dots\}$$

where the c-s are \perp , \top , or numbers

- Between two program points, the transfer function then takes us between

$$\{v_1=c_1, v_2=c_2, v_3=c_3, \dots\}$$

and

$$\{v_1'=c_1', v_2'=c_2', v_3'=c_3', \dots\}$$

- Can we confidently say that

$$\{v_1=c_1, v_2=c_2, v_3=c_3, \dots\} \sqsupseteq \{v_1'=c_1', v_2'=c_2', v_3'=c_3', \dots\}$$

so that the transfer function will work towards a guaranteed, finite goal?



Products of lattices

- Lattices are partial orders, they consist of a set, and an order (which fulfills the constraint that all subsets have a g.l.b. and l.u.b.)
- The sets have Cartesian products
$$L_1 \times L_2 = \{ (x,y) \mid x \in L_1, y \in L_2 \}$$
$$L_1 \times L_2 \times L_3 = \{ (x,y,z) \mid x \in L_1, y \in L_2, z \in L_3 \}$$
...and so on...
- If L_1, \dots, L_n are (complete) lattices, their Cartesian product is a (complete) lattice as well, with the order defined so that the n-tuples
$$(y_1, y_2, \dots, y_n) \supseteq (x_1, x_2, \dots, x_n)$$
if and only if
$$y_1 \supseteq x_1, y_2 \supseteq x_2, \dots, y_n \supseteq x_n$$
- In other words, if we apply a monotonic function to all the elements in the n-tuple from a lattice product, the n-tuples preserve the same order



The whole meet operator

- When two control paths meet up, their respective constant-information sets might be something like

$$\{x = 3, y = \top, z = 5\}$$

and

$$\{x = 3, y = 2, z = \perp\}$$

- The CF meet operator applies the constant-glb relation to all pairs

$$\{x = 3, y = \top, z = 5\}$$

$$\sqcap \{x = 3, y = 2, z = \perp\}$$

$$= \{x = 3, y = 2, z = \perp\}$$

$$\text{glb}(3,3) = 3, \text{glb}(\top,2) = 2, \text{glb}(5,\perp) = \perp$$



Convergence

- The whole CF lattice is ordered by the relation from the constant-lattices of each of its variables
- The meet op. (glb) of the constant-ness states of one variable is monotonic
 - It never goes from “X = 24” to “X is still unknown” (\top)
 - It never goes from “X is not constant” (\perp) to “X is 62” either
- Therefore, the combination of individual meets for all the variables is monotonic also
 - Same rationale, it’s not going to go from a “more specific” point
 $\{x = 3, y = 2, z = \perp\}$
to a “less specific” point like
 $\{x = 3, y = 2, z = 5\}$
because that’s not what comes out of $\{z = \perp\} \sqcap \{z = 5\}$



The analyses we have seen

- Ok... to recap what we know about all this stuff now
 - Domains are made up of elements that represent information from the source code, they are sets of
 - Live variables (Liveness)
 - Pairs of variables (Copy Propagation)
 - Expressions (Available Expressions)
 - Definitions / assignments (Reaching Definitions)
 - Constant-information about variables (Constant Folding)



Transfer functions

- Descriptions of how statements affect the sets at program points before and after

LV: $lv\ after = \{ lv\ after - var.\ defined \} \cup \{ var.\ used \}$
 CP: $copies\ after = \{ copies\ before - copies\ ruined \} \cup \{ copies\ made \}$
 AE: $expr.\ after = \{ expr.\ before - expr.\ ruined \} \cup \{ expr.\ evaluated \}$
 RD: $defs\ after = \{ defs\ before - defs\ overwritten \} \cup \{ defs\ made \}$
 CF: $const\ after = \{ const\ before - non-const\ found \} \cup \{ const\ made \}$

or, with more conventional notation

LV: $in[l] = \{ out[l] - def(l) \} \cup use(l)$ (Backward)
 CP: $out[l] = \{ in[l] - kill(l) \} \cup gen(l)$ (Forward)
 AE: $out[l] = \{ in[l] - kill(l) \} \cup gen(l)$ (Forward)
 RD: $out[l] = \{ in[l] - kill(l) \} \cup gen(l)$ (Forward)
 CF: $out[l] = \{ in[l] - kill(l) \} \cup gen(l)$ (Forward)

(what each analysis kills and generates follows from how the instructions affect its domain)

Meet operators

- Descriptions of how to combine control flow paths, when they cross
 - LV: \cup (variables used along any path)
 - CP: \cap (copies made along every path)
 - AE: \cap (expressions available along every path)
 - RD: \cup (definitions coming from any path)
 - CF: \sqcap_{CF} (glb relation from constant-ness lattices)

Monotonicity

- Guarantee that iterating over the data flow equations take program points strictly toward one end of the domain's order
- The contributions from instructions are static, the source code doesn't change during analysis
- The meet operators only contribute in one direction
 - LV: $x \cup y$ is glb in power set lattice of variables
 - CP: $x \cap y$ is glb in power set lattice of copies
 - AE: $x \cap y$ is glb in power set lattice of expressions
 - RD: $x \cup y$ is glb in power set lattice of definitions
 - CF: $x \sqcap_{CF} y$ is glb in the product of constant-lattices we discussed
- None of these analyses will run forever



Ups and downs

- Up until this point, I waved my hands at the beginning and pointed out that we can arrange our lattice orders
 - With \emptyset at the bottom and the set all elements at the top
 - With \emptyset at the top and the set of all elements at the bottom
 - With g.l.b. and l.u.b. determining the direction when points are combined
 - An idea of a “Top” (\top) and “Bottom” (\perp)
 - Some matching, vague notion of “more” and “less” program information

and suggested that all of these can be rearranged as a matter of notation

- I have played fast and loose with this because we haven’t said anything where it matters
 - Same kind of nuisance as talking about stacks that grow into lower addresses, it’s disruptive to stop and remember that up is down and plus is minus every 2 minutes



Making a choice

- Consistency matters more in an overview, so let's standardize it a bit
- Choose the top \top to be the most an analysis can hope for
- Choose the meet operator \sqcap to be the greatest lower bound of a lattice subset
- Choose the bottom \perp to be the worst outcome

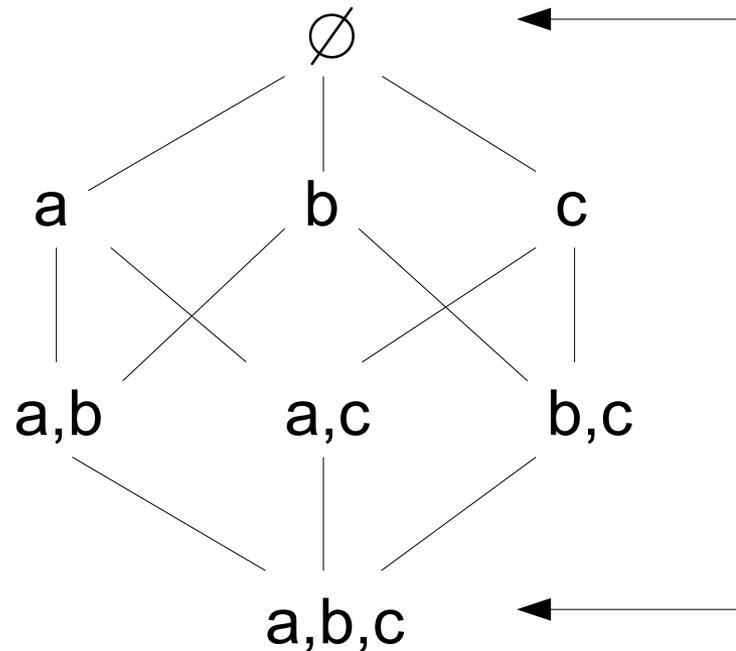
Why choose these?

- The book draws with up/down in these directions (Fig. 9.22, p.622)
- We need a convention before discussing “precision”
- On the other hand
 - Several fixed points can solve the same system of constraint equations
 - The one that our iterative method finds is called the *maximal fixed point*
 - It is “maximal” in the sense of being at the end of a chain of states which is as long as possible
 - Paradoxically, that puts it closest to the order point called “bottom”
(*sigh*)
 - That’s the way it goes



Interpretations from top to bottom

For live variables:



Most useful:

No variables are needed

Most careful:

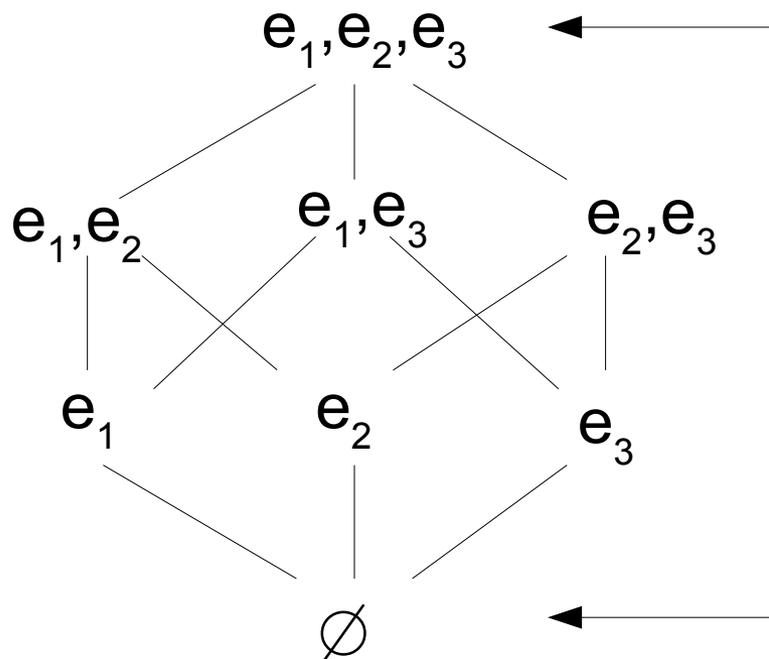
All variables are needed



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Interpretations from top to bottom

For available expressions:



Most useful:
All expressions
can be re-used

Most careful:
No expressions
can be re-used

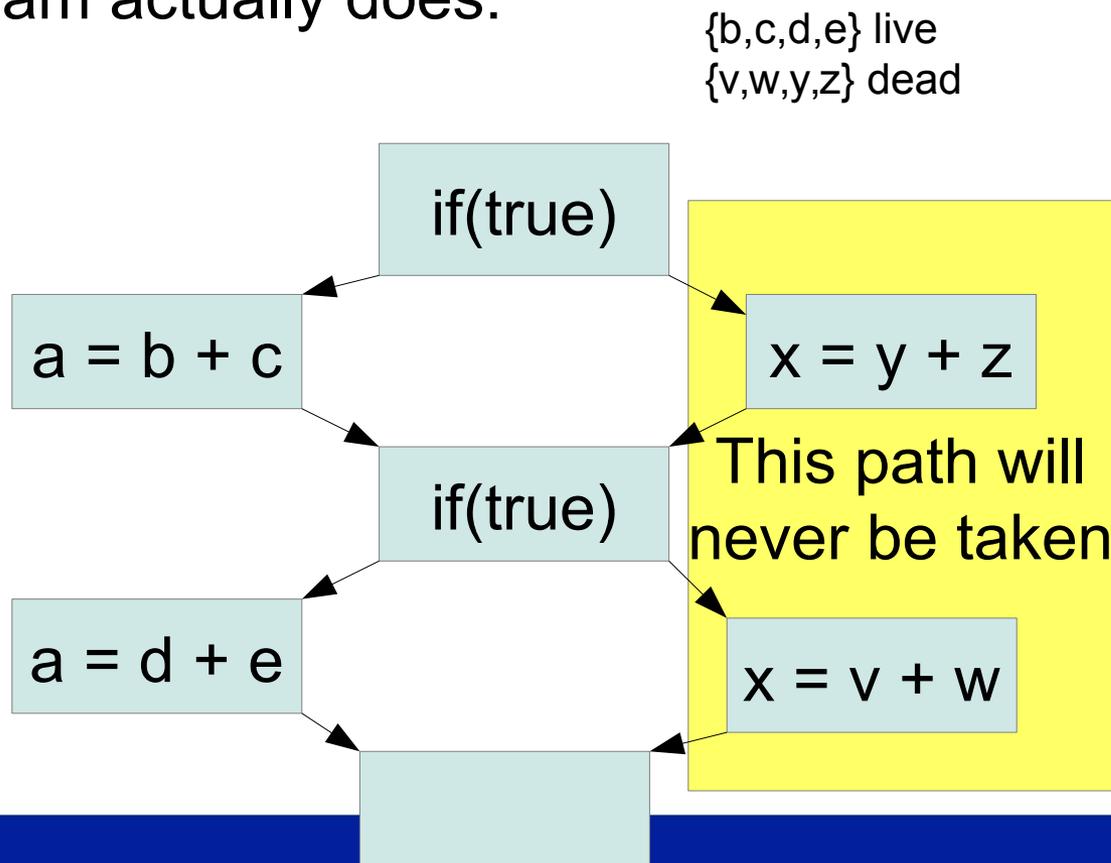


Several solutions

- As a trivial example, take the “program” $x = y+z$, and consider liveness
 - We get 1 constraint equation: $\text{in} = \{\text{out} - x\} \cup \{y,z\}$
- Start from $\text{out} = \{x,y,z\}$
 - $\{y,z\}$ are live here
 - $x = y + z$
 - $\{x,y,z\}$ are live here
- Start from $\text{out} = \{\}$
 - $\{y,z\}$ are live here
 - $x = y + z$
 - $\{\}$ is live here
- These are both solutions to the data flow equation
- Apply the constraints again, nothing changes in either case

What's the *best* solution?

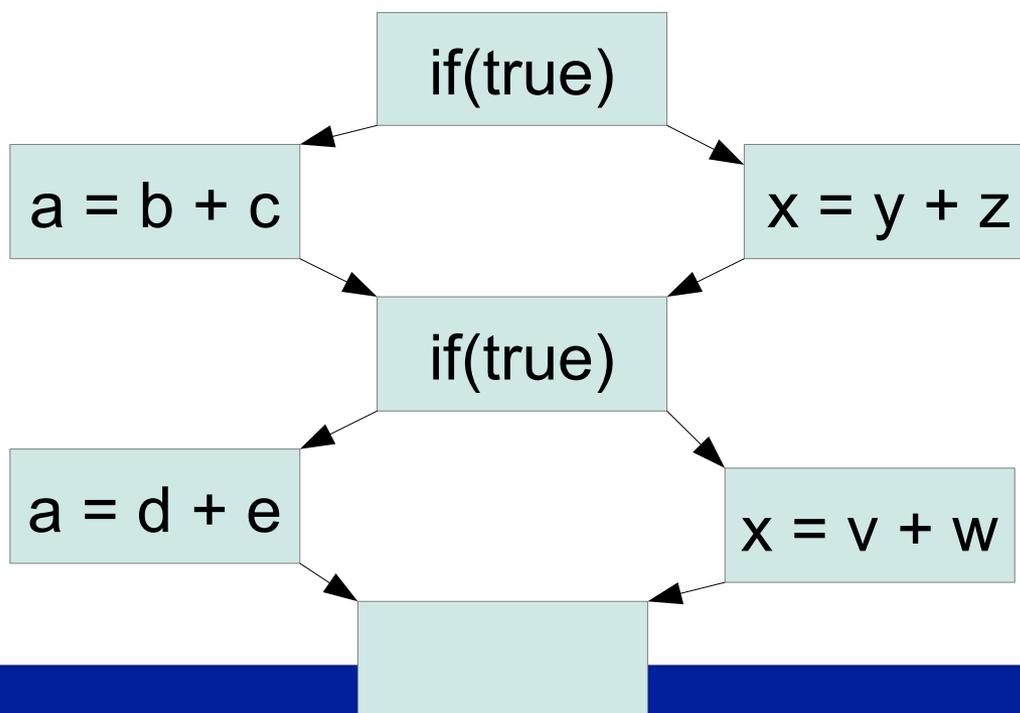
- That would be the one which captures what the program actually does:



Which solution does the framework suggest?

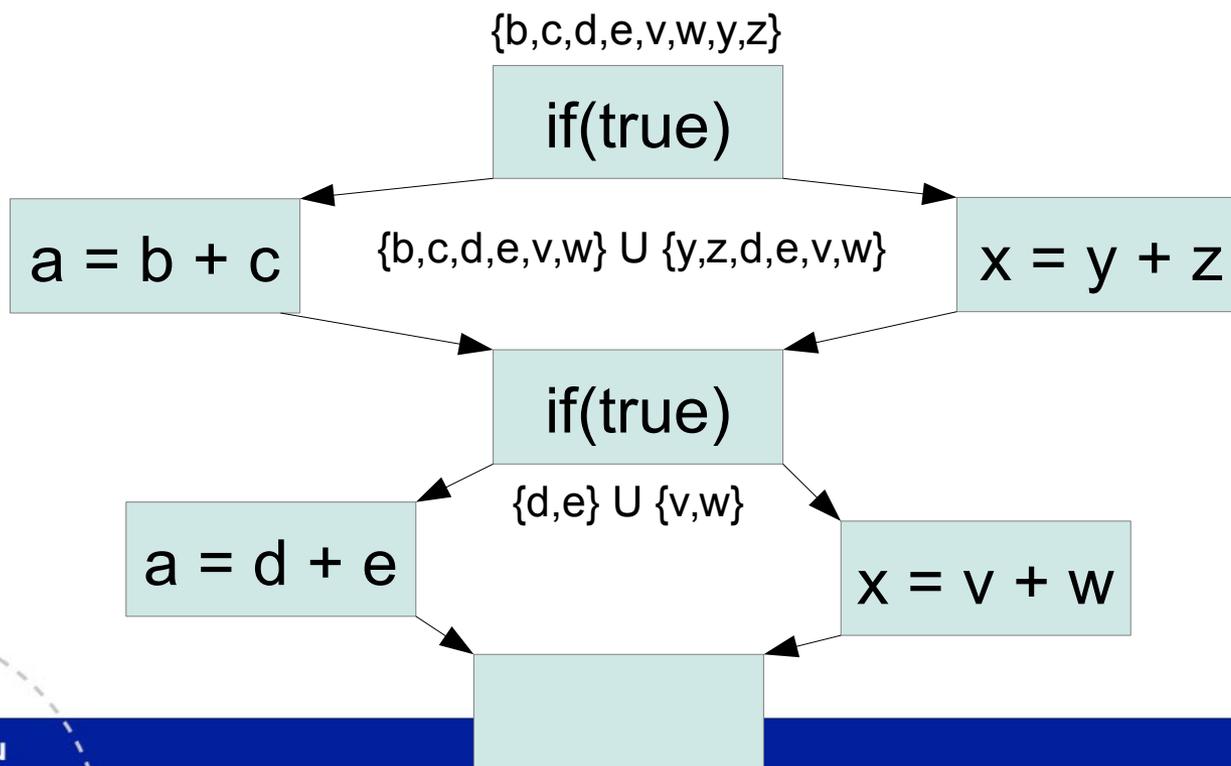
- That's the one which comes from considering the meet operator applied to all possible paths

$$\{b,c,d,e\} \cup \{b,c,v,w\} \cup \{y,z,d,e\} \cup \{y,z,v,w\} = \{b,c,d,e,v,w,y,z\}$$



Which solution do we compute?

- The one that comes from starting every point at \top , and iterating with \sqcap until there's no change



Names for those

- In order, we can call them
 - IDEAL (The one that accurately reflects the code)
 - Meet-Over-Paths (The one that considers every path)
 - Maximal Fixed Point (The one we get by iterating from \top)
- IDEAL is the *most precise* solution, because it would tell us exactly what the program means
 - Sadly, that can not be computed automatically
- MOP would be as close as we could get by static inspection
 - Trace every possible execution individually, apply \sqcap between all
 - Sadly, we can't compute that either
 - “Every possible execution” includes going through every (dynamically determined) loop once, two times, three times, ... and on to infinity

Their relationship

- The solution we *do* get (the way we've been working), is the MFP

The iterations for a point go through a descending chain

$T \supseteq F(T) \supseteq F(F(T)) \supseteq \dots \supseteq \text{MFP}$ (← where we stop iterating)

- This is excessively careful

- It combines paths as soon as possible, thereby losing precision
- We'll see in a minute

- It's safe

$\text{MOP} \supseteq \text{MFP}$

- They're often the same (as in all our examples so far)
- When they differ, MOP is closer to the most useful end of the order

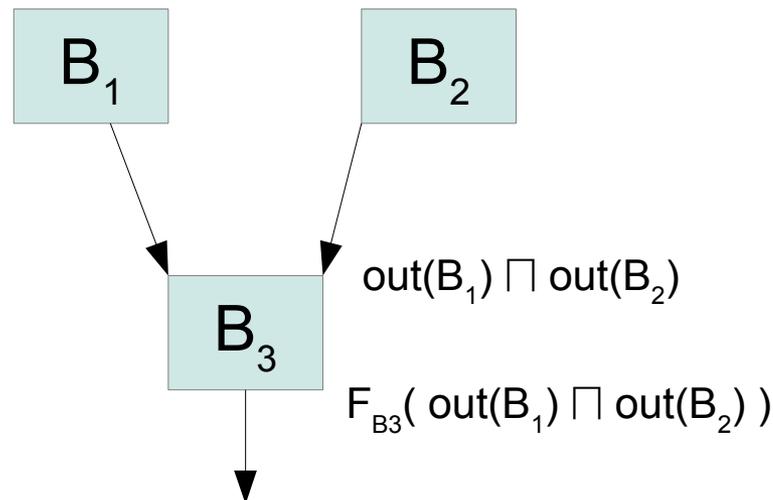
- MOP applies constraints along paths never taken, when there are any

$\text{IDEAL} \supseteq \text{MOP} \supseteq \text{MFP}$



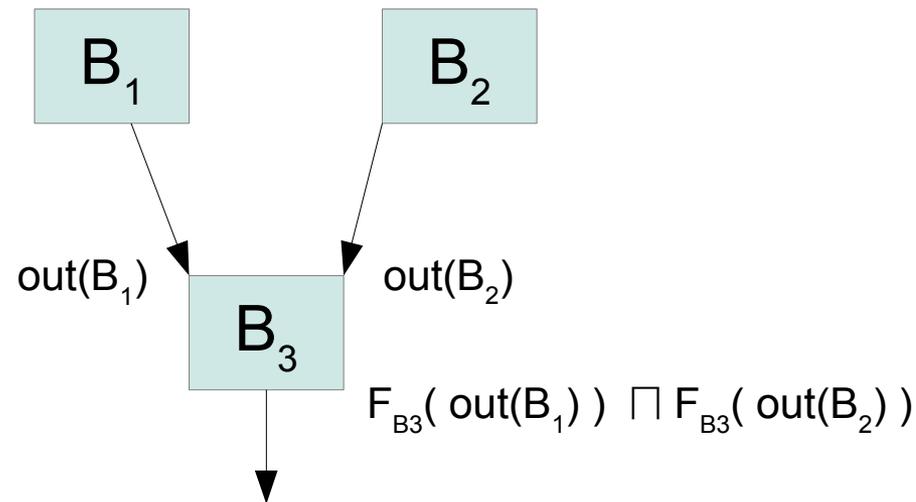
MFP evaluation

- MFP computes the function of B_3 on the combination of $\text{out}(B_1)$ and $\text{out}(B_2)$



MOP evaluation

- MOP computes the function of B_3 by combining
 - B_3 's effect on $\text{out}(B_1)$
 - B_3 's effect on $\text{out}(B_2)$



Distributivity

- If F is a distributive function *wrt.* \sqcap , then

$$F(x \sqcap y) = F(x) \sqcap F(y)$$

(that's the definition of distributive)

- When the function representing an analysis has this property, then the MFP solution (we can compute) is the same as the MOP solution (we can't compute)
- When
 - the function is just adding and removing elements to sets
 - the operator is just simple combinations of set elements

distributivity follows

If F is something like “delete element x ”, then practically by common sense,

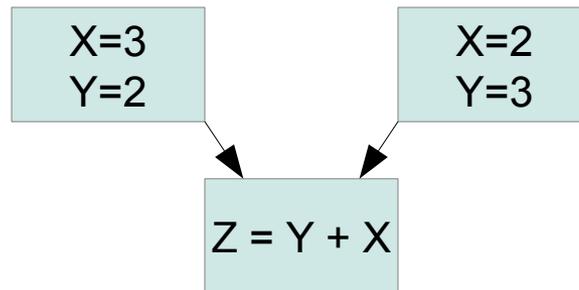
$$F(\{x,y,z\} \cup \{v,w,x\}) = \{v,w,y,z\}$$

$$F(\{x,y,z\}) \cup F(\{v,w,x\}) = \{y,z\} \cup \{v,w\} = \{v,w,y,z\}$$



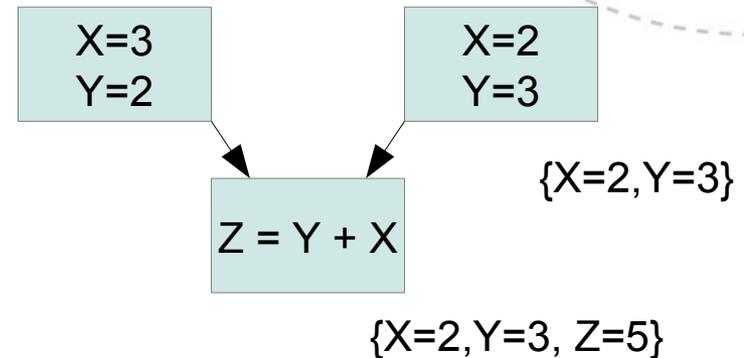
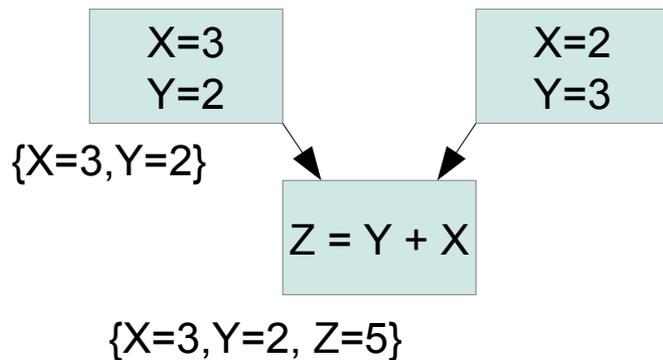
Distributivity vs Constant Folding

- LV, CP, AE, RD all give MFP=MOP, because their functions are distributive *wrt.* their respective union/intersection meet operators
- The constant-detecting scheme is not distributive *wrt.* its funny meet operator
- Witness:



Distributivity vs Constant Folding

- By Meet-Over-Paths, here are the two paths



This gives the MOP solution

$$\{X=3, Y=2, Z=5\} \sqcap_{CF} \{X=2, Y=3, Z=5\} = \{X=\perp, Y=\perp, \mathbf{Z=5}\}$$

Distributivity vs Constant Folding

- The Maximal Fixed Point solution is less informative, it misses that $Z=5$ regardless of which way it's calculated

