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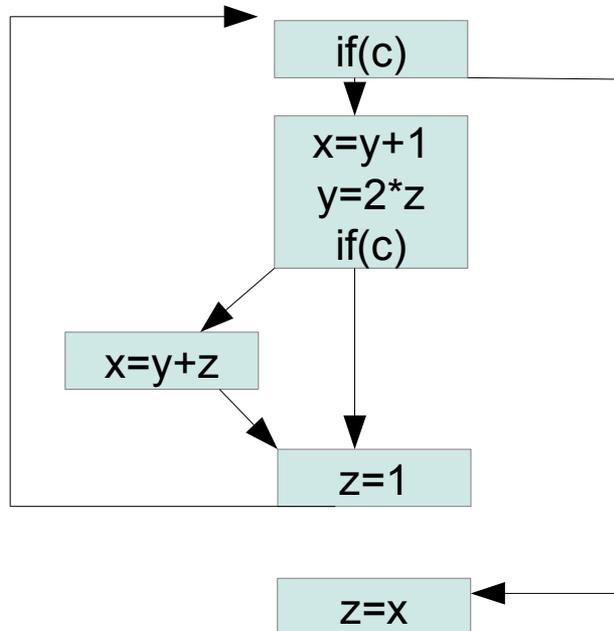
## **Liveness revisited**

# Putting “the framework” into practice

- Having introduced some ideas and notation, it might be useful to visit the liveness analysis again
- This time, we'll apply the notation and connect it to the (somewhat abstract) argument that it works
- Thus, we can use the same ideas and notation for other analysis instances next time

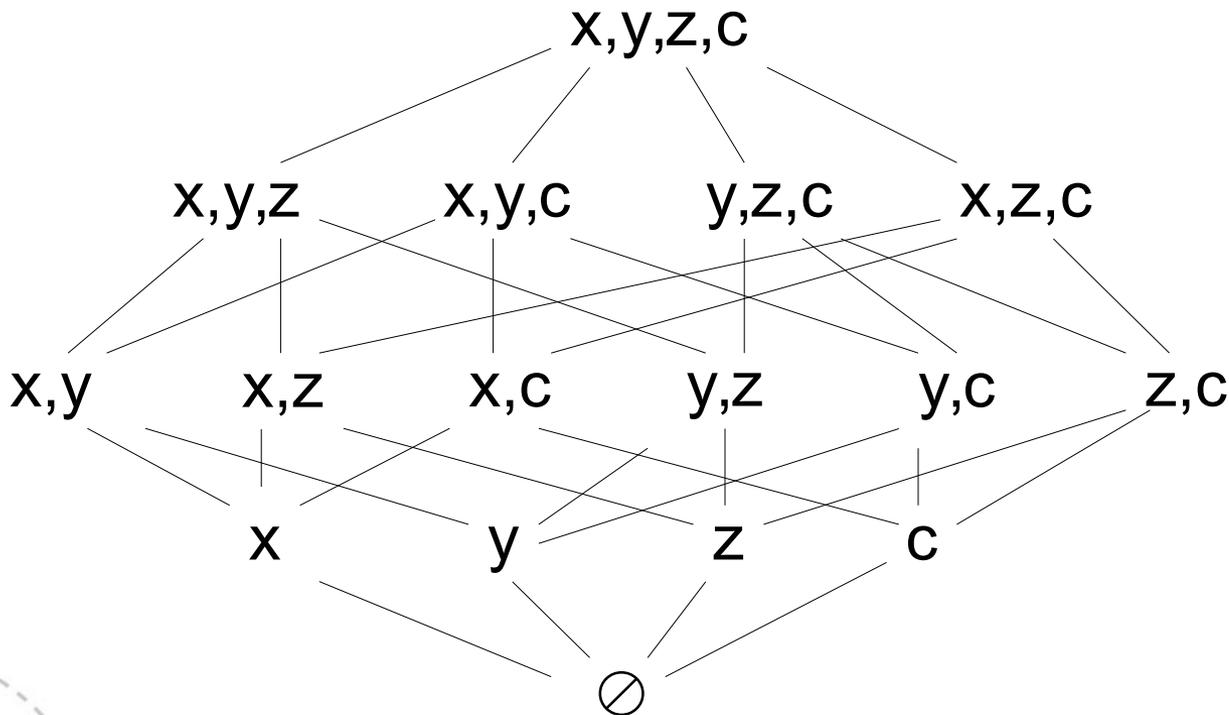
# Slightly modified liveness example

- I have removed the variable 'd', to have fewer variables to deal with
  - This makes the program a bit stupider, but it'll work for illustration



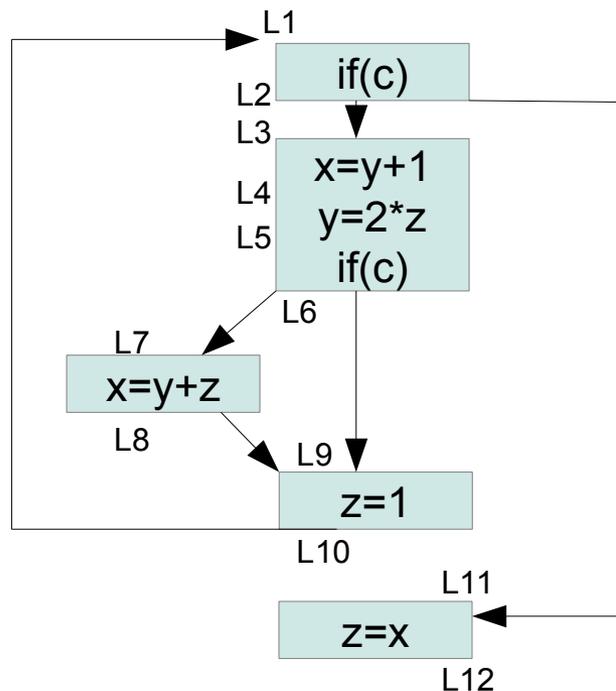
# The power set lattice

- This is why I want one less variable to deal with



# Name all the program points

so that we can talk about them in multiple diagrams



# Recipe for the constraints

- Constraints from instructions:

$$\text{in}[I] = \{\text{out}[I] - \text{def}[I]\} \cup \text{use}[I]$$

- Constraints from control flow:

$$\text{out}[B] = \bigcup \text{in}[B'] \mid B' \text{ is a successor of } B$$



# Data flow equations for each point

$$L1 = L2 \cup \{c\}$$

$$L2 = L3 \cup L11$$

$$L3 = \{L4 - x\} \cup \{y\}$$

$$L4 = \{L5 - y\} \cup \{z\}$$

$$L5 = L6 \cup \{c\}$$

$$L6 = L7 \cup L9$$

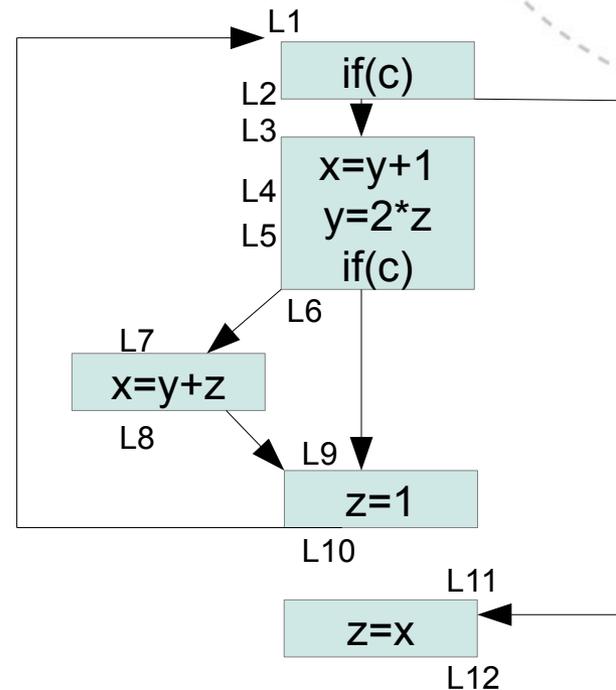
$$L7 = \{L8 - x\} \cup \{y, z\}$$

$$L8 = L9$$

$$L9 = \{L10 - z\}$$

$$L10 = L1$$

$$L11 = \{L12 - z\} \cup \{x\}$$



# An initial assumption

- Last time, I took the commonsensical approach that the variables will see some future use we know nothing about
- This was a tiny fib, so as to get to the data flow thing without waving my hands around what this program ostensibly “does”
- When you’re analyzing an entire function/program/translation unit, it is actually quite safe to say that nothing will be used again at the end



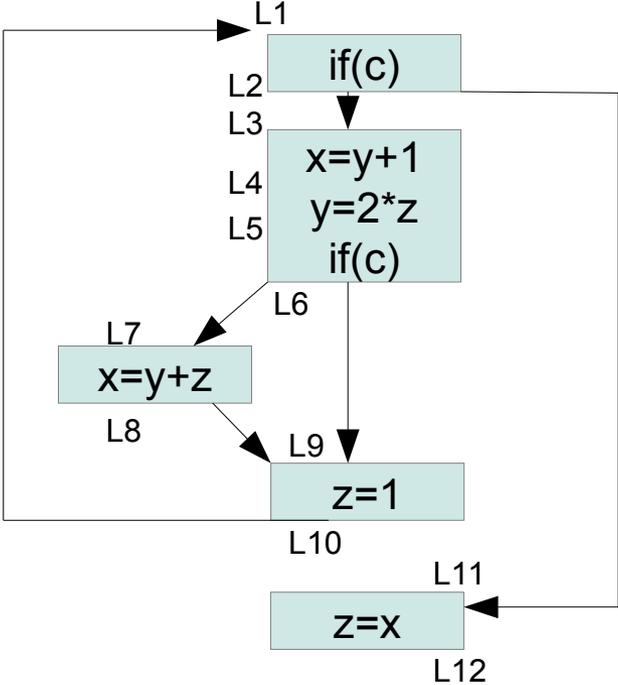
# The handwaving

- Since we're re-doing this with all the trimmings now, please make-believe that this is an independent program unit
- That is pretty contrived
  - In the context of optimizations, the entire code should actually be cut away, it does nothing observable
  - If we can ignore that, while still pretending to be interested in the liveness result, we can work out the constraints from the more appropriate starting point of the empty set
- Yes, I know it's a bit corny to optimize pointless code
- Keeps the example small, though



# Iteration 1, L11

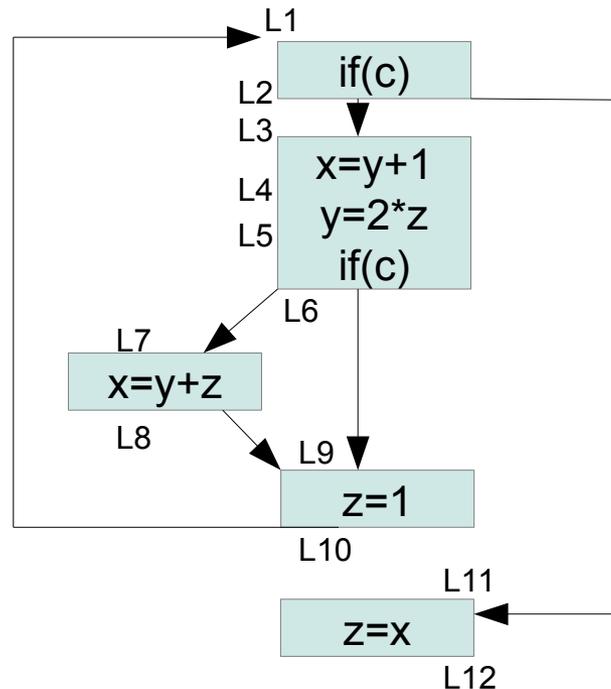
- L1 = L2 ∪ {c}
- L2 = L3 ∪ L11
- L3 = {L4 - x} ∪ {y}
- L4 = {L5 - y} ∪ {z}
- L5 = L6 ∪ {c}
- L6 = L7 ∪ L9
- L7 = {L8 - x} ∪ {y,z}
- L8 = L9
- L9 = {L10 - z}
- L10 = L1
- L11 = {L12 - z} ∪ {x}



- L1 = {}
- L2 = {}
- L3 = {}
- L4 = {}
- L5 = {}
- L6 = {}
- L7 = {}
- L8 = {}
- L9 = {}
- L10 = {}
- L11 = {x}
- L12 = {}

# Iteration 1, L10 → L3

$L1 = L2 \cup \{c\}$   
 $L2 = L3 \cup L11$   
 $L3 = \{L4 - x\} \cup \{y\}$   
 $L4 = \{L5 - y\} \cup \{z\}$   
 $L5 = L6 \cup \{c\}$   
 $L6 = L7 \cup L9$   
 $L7 = \{L8 - x\} \cup \{y, z\}$   
 $L8 = L9$   
 $L9 = \{L10 - z\}$   
 $L10 = L1$   
 $L11 = \{L12 - z\} \cup \{x\}$

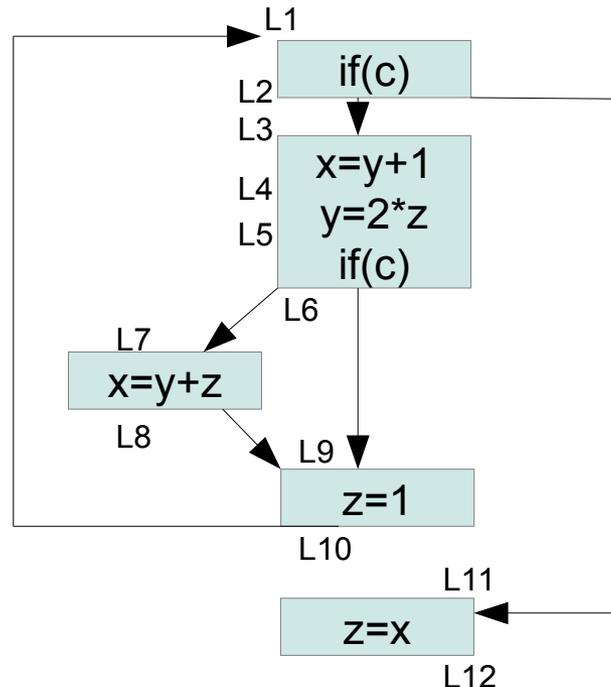


$L1 = \{\}$   
 $L2 = \{\}$   
 $L3 = \{y, z, c\}$   
 $L4 = \{z, c\}$   
 $L5 = \{y, z, c\}$   
 $L6 = \{y, z\}$   
 $L7 = \{y, z\}$   
 $L8 = \{\}$   
 $L9 = \{\}$   
 $L10 = \{\}$   
 $L11 = \{x\}$   
 $L12 = \{\}$



# Iteration 1, L2,L1

$L1 = L2 \cup \{c\}$   
 $L2 = L3 \cup L11$   
 $L3 = \{L4 - x\} \cup \{y\}$   
 $L4 = \{L5 - y\} \cup \{z\}$   
 $L5 = L6 \cup \{c\}$   
 $L6 = L7 \cup L9$   
 $L7 = \{L8 - x\} \cup \{y,z\}$   
 $L8 = L9$   
 $L9 = \{L10 - z\}$   
 $L10 = L1$   
 $L11 = \{L12 - z\} \cup \{x\}$

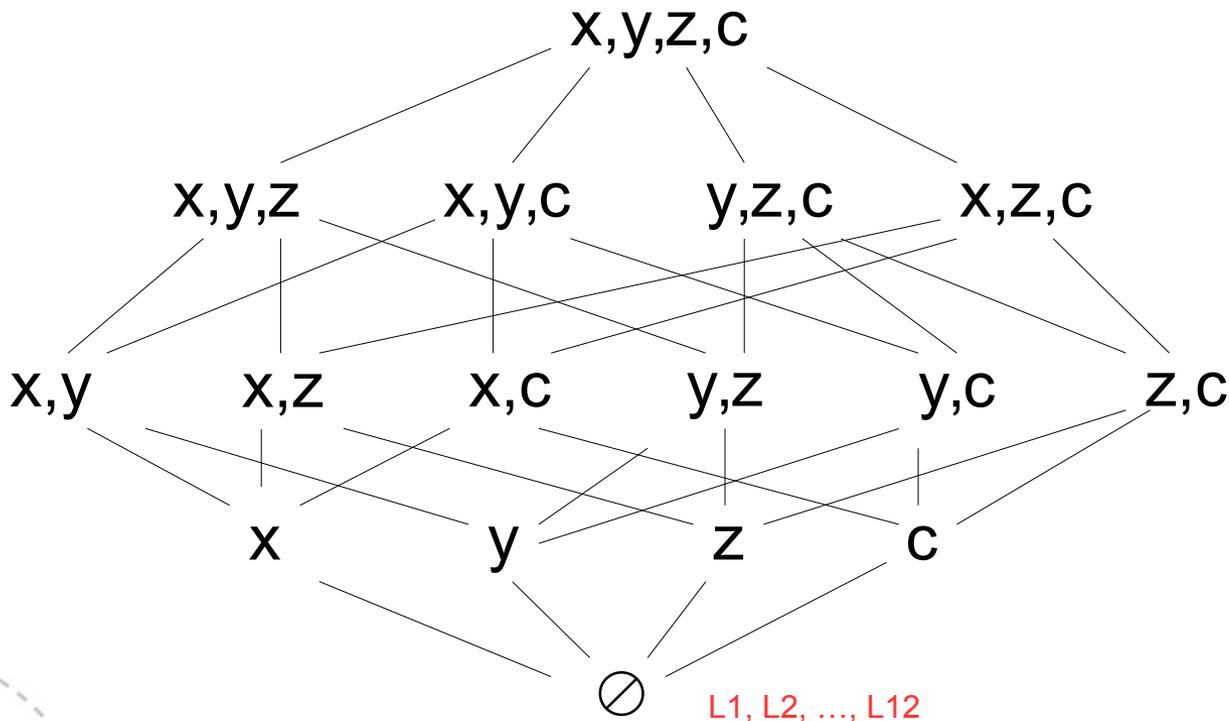


$L1 = \{x,y,z,c\}$   
 $L2 = \{x,y,z,c\}$   
 $L3 = \{y,z,c\}$   
 $L4 = \{z,c\}$   
 $L5 = \{y,z,c\}$   
 $L6 = \{y,z\}$   
 $L7 = \{y,z\}$   
 $L8 = \{\}$   
 $L9 = \{\}$   
 $L10 = \{\}$   
 $L11 = \{x\}$   
 $L12 = \{\}$



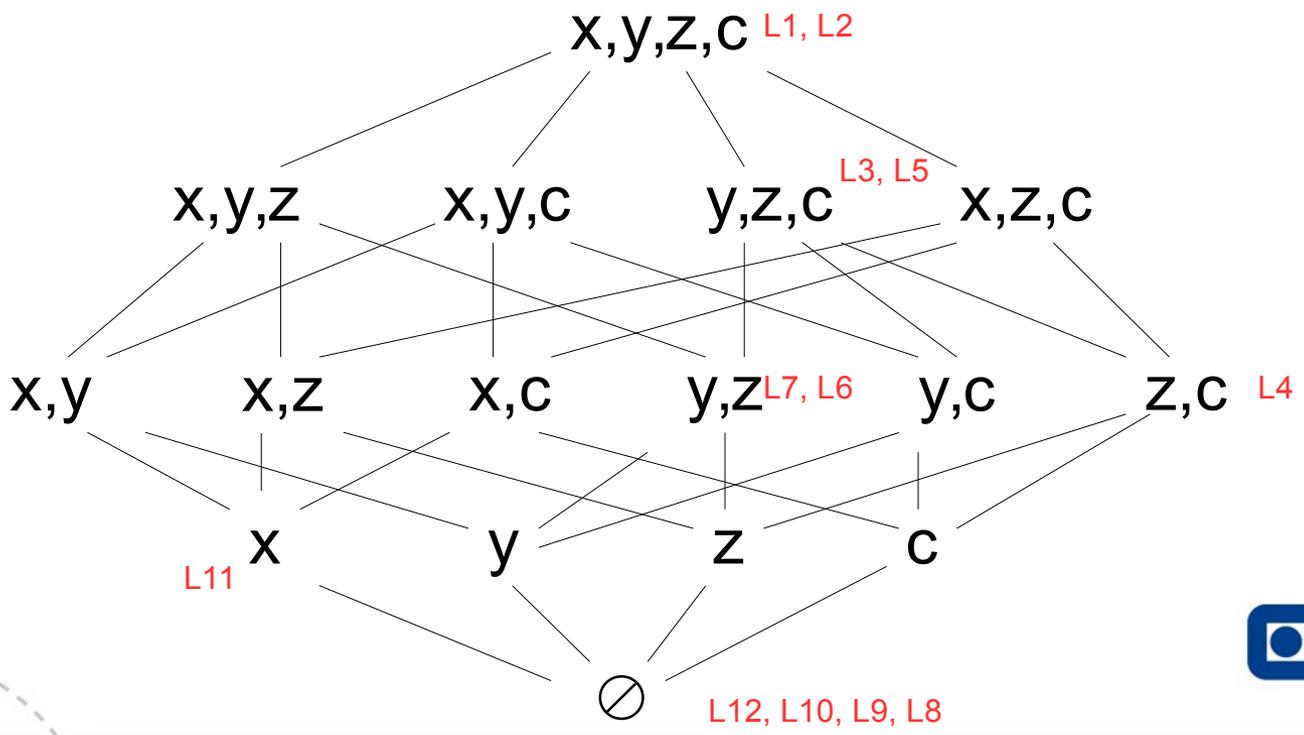
# The program points have moved

- We started them out at the bottom:



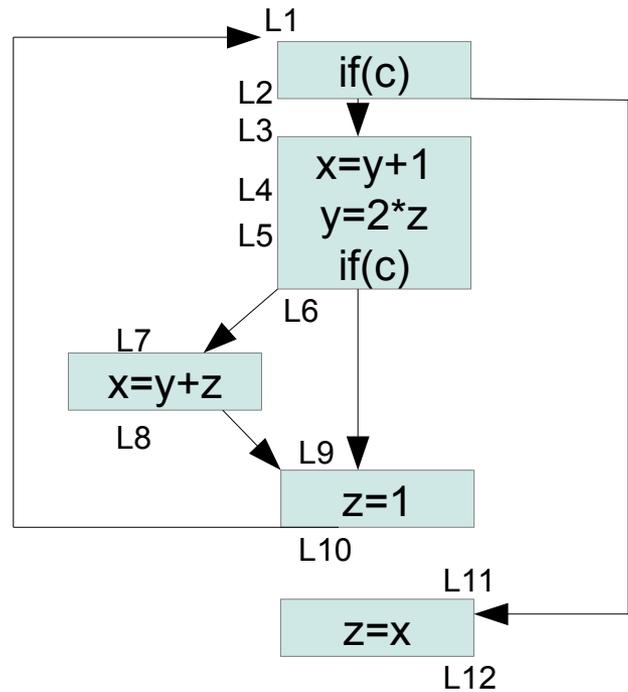
# The program points have moved

- Now some of them are scattered around



# Iteration 2

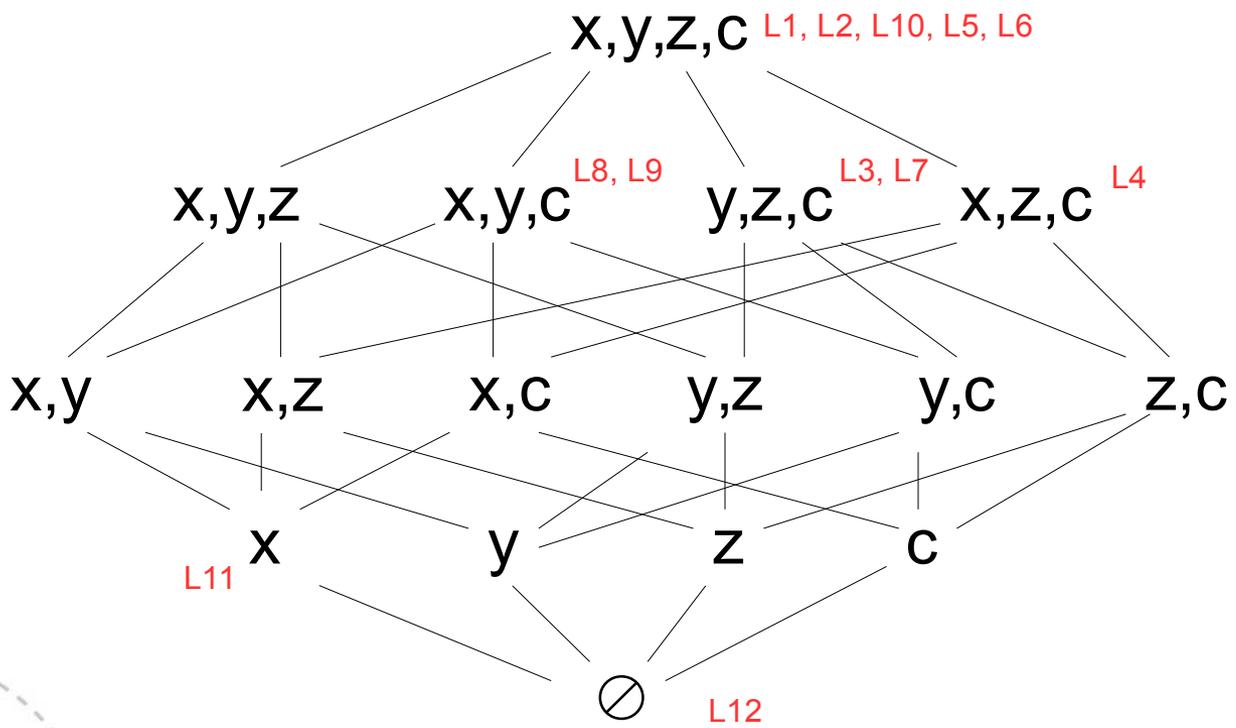
- L1 = L2 ∪ {c}
- L2 = L3 ∪ L11
- L3 = {L4 - x} ∪ {y}
- L4 = {L5 - y} ∪ {z}
- L5 = L6 ∪ {c}
- L6 = L7 ∪ L9
- L7 = {L8 - x} ∪ {y,z}
- L8 = L9
- L9 = {L10 - z}
- L10 = L1
- L11 = {L12 - z} ∪ {x}



- L1 = {x,y,z,c}
- L2 = {x,y,z,c}
- L3 = {y,z,c}
- L4 = {x,z,c}
- L5 = {x,y,z,c}
- L6 = {x,y,z,c}
- L7 = {y,z,c}
- L8 = {x,y,c}
- L9 = {x,y,c}
- L10 = {x,y,z,c}
- L11 = {x}
- L12 = {}

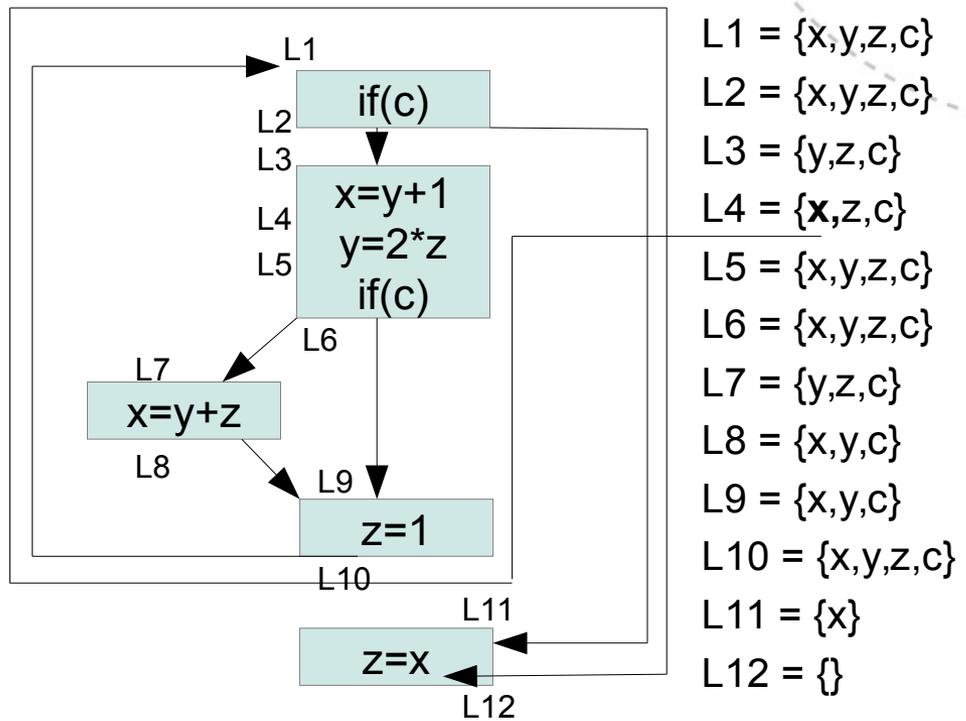
# The program points have moved again

- Notice that they're only heading towards the top



# We've reached a fixed point

Analysis detected that there is an execution where  $x=y+1$  is used



# So, the argument goes

- If the transfer function only moves program points up the lattice, they will either
  - Come to a fixed point before they reach the top of the lattice
  - Reach the top of the lattice, and have no place left to go
- Analyses that use transfer functions which have this monotonicity will always terminate at a fixed point



# That was a lot of notation for a simple observation

- The goal is generality
- If liveness were all we cared about, this would be overkill
- *Reaching Definitions*, *Available Expressions* and *Constant Folding* are the same way, just with other choices of operators, sets, transfer functions and directions
- It's hopefully a little easier to remember them as 4 cases of 1 method rather than 4 separate approaches to separate problems



# Next time

- With most of the notation in place, we'll discuss the other analysis instances within this same terminology, to highlight what they have in common, and how they differ